PERSONAL INFORMATION

Pancho Nikolaev Dachkinov



pdachkinov@icloud.com

Sex male | Date of birth 22/03/1993 | Nationality Bulgarian

WORK EXPERIENCE

October 2022 - present

Assistant Professor

Institute of Robotics – Bulgarian Academy of Sciences (address: Bl. 2, Acad. G. Bonchev Str., Sofia, PoB 79, Bulgaria website: http://www.ir.bas.bg/)

Research

Business or sector Research Institute in the field of Robotics and Applied Sciences

October 2016 - September 2019 Young Researcher

Institute of Robotics – Bulgarian Academy of Sciences (address: Bl. 2, Acad. G. Bonchev Str., Sofia, PoB 79, Bulgaria website: http://www.ir.bas.bg/)
Research

Business or sector Research Institute in the field of Robotics and Applied Sciences

EDUCATION AND TRAINING

October 2019 – September 2022

Doctor of Philosophy

Kyushu Institute of Technology, Graduate School of Life Science and System Engineering, Kitakyushu, Japan

• Investigating the Properties of Compliant Mechanisms, Biomechanics, Anatomy

2-16 - 2018

Masters in Computer Aided Design and Technologies in Industry

Technical University of Sofia, Bulgaria

• 3D Printing, CAD Modelling, Robotics

October 2012 - 2016

Bachelor in Logistics Engineering

Technical University of Sofia, Bulgaria

Logistics, Barcode Scanning, Manufacturing Autonomation

PERSONAL SKILLS

Mother tongue(s)

Bulgarian

Other language(s)

UNDERSTANDING		SPEAKING		WRITING
Listening	Reading	Spoken interaction	Spoken production	
Excellent	Excellent	Excellent	Excellent	Excellent



Curriculum Vitae

Communication skills

• good communication skills gained through my experience as young research and participant in Horizon 2020 MSCA. Member of MCAA.

Organisational / managerial skills

- leadership skills acquired as a President of the Foreign Student Association at Kyushu Institute of Technology from April 2021 to March 2022.
- Good organisational skills gained during the doctoral course.

Computer skills

- good command of Microsoft Office™ tools
- good at Autodesk Inventor Professional
- good with 3D Printing software

Other skills

- Problem solving
- Critical thinking

Driving licence

• B

ADDITIONAL INFORMATION



Publications

- Design and Motion Capabilities of an Emotion- Expressive Robot EmoSan; Toyama, Japan; Pancho Dachkinov, Tanio Tanev, Anna Lekova, Dondogjamts Batbaatar, Hiroaki Wagatsuma; 2018.
- Design and analysis of 3D printed and assembled rotational units. applications for mechanisms used in robotics - I. Chavdarov, P. Dachkinov, V. Trenev, A. Krastev, G. Elenchev;
- Augmented intelligence for teaching robots by imitation Prof. Lekova A. PhD1, Prof. Pavlov V. PhD, Assoc. Prof. Chavdarov I. PhD, Assoc. Prof. Krastev A. PhD, Datchkinov P, Stoyanov I.;
- S. Kasai, P. Dachkinov, K. Tanaka and H. Wagatsuma, "A Systematic Analysis of the Knee Support Exoskeleton Based on Multibody Dynamics Toward Personalization with 3D printed Spring-Damper Components," "International Conference on Artificial Life and Robotics", (ICAROB2022).
- P. Dachkinov, S. Kasai, K. Tanaka and H. Wagatsuma, "A computational model of 3d printing orthoses associated with a systematic structural analysis toward reverse engineering oriented production," ICIC-ELB, Vol.13, No.7, July 2022, ISSN 2185-2766.
- P. Dachkinov, S. Kasai, K. Tanaka and Wagatsuma, "Flexible Bar Geometric Designs for Personalized Knee Orthoses Inspired by Compliant Mechanisms," Journal of Robotics, Networking and Artificial Life, in press.
- Bhattacharjee, P. Dachkinov, H. Wagatsuma and B. Bhattacharya, "3D PRINTED BEAMS WITH VARIABLE INFILL DENSITIEs," International Journal of Engineering Advanced Research (IJEAR), 2022, 2710-7167.
- P. Dachkinov, A. Bhattacharjee, B. Bhattacharya and H. Wagatsuma, "A Multi-Material Joint System as a Three-Dimensional Spring-Damper Compliant Mechanism Toward Functional Versatility,"
 "Journal of Advances in Artificial Life Robotics," JAALR, Volume 3, Issue 2, September 2022, pp. 67– 73, online ISSN 2435-8061; ISSN-L 2435-8061.

Projects

Conferences

■ Participant in Horizon 2020 MSCA RISE Project 2017 – 2019.

Symposiums

- Design and Motion Capabilities of an Emotion- Expressive Robot EmoSan; Pancho Dachkinov, Tanio Tanev, Anna Lekova, Dondogjamts Batbaatar, Hiroaki Wagatsuma; SCIS&ISIS2018, Toyama, Japan, 2018.
- P. Dachkinov, A. Bhattacharjee B. Bhattacharya and H. Wagatsuma, "A Knee Joint Inspired Design of a Compliant Cross-Spring Pivot," "International Symposium of Applied Engineering and Sciences," (SAES 2020).
- P. Dachkinov, A. Bhattacharjee, B. Bhattacharya and H. Wagatsuma, "A Three-Dimensional Design and Analysis of a Multi-material Compliant Joint for Precision Engineering Applications", "International Symposium on Robotics in Industry, Agriculture and Healthcare" (ISHIAH2022).
- S. Kasai, P. Dachkinov, K. Tanaka and H. Wagatsuma, "The Effectiveness of Force Measurement System by Using Programmable Actuators for 3D Printed Compliant Mechanisms", "International Symposium of Applied Engineering and Sciences," (SAES 2021).